

```
> with(linalg);
```

```
\QTR{cstyle2}{Warning, the protected names norm and trace have been redefined and  
unprotected}\QTR{cstyle2}{  
}
```

[*BlockDiagonal, GramSchmidt, JordanBlock, LUdecomp, QRdecomp, Wronskian, addcol, addrow, adj, adjoint, angle, augment, backsub, band, basis, bezout, blockmatrix, charmat, charpoly, cholesky, col, coldim, colspace, colspan, companion, concat, cond, copyinto, crossprod, curl, definite, delcols, delrows, det, diag, diverge, dotprod, eigenvals, eigenvalues, eigenvectors, eigenvects, entermatrix, equal, exponential, extend, ffgausselim, fibonacci, forwardsub, frobenius, gausselim, gaussjord, geneqns, genmatrix, grad, hadamard, hermite, hessian, hilbert, htranspose, ihermite, indexfunc, innerprod, intbasis, inverse, ismith, issimilar, iszero, jacobian, jordan, kernel, laplacian, leastsqrs, linsolve, matadd, matrix, minor, minpoly, mulcol, mulrow, multiply, norm, normalize, nullspace, orthog, permanent, pivot, potential, randmatrix, randvector, rank, ratform, row, rowdim, rowspace, rowspan, rref, scalarmul, singularvals, smith, stackmatrix, submatrix, subvector, sumbasis, swapcol, swaprow, sylvester, toeplitz, trace, transpose, vandermonde, vecpotent, vectdim, vector, wronskian*]

```
> A:=matrix(6,6,[23,76,23,-92,38,-3,-8,-32,-10,40,-17,1,-34,-124,-36,15  
> 2,-64,6,-1,-7,-2,10,-4,0,23,86,26,-104,45,-4,3,14,4,-16,7,2]);
```

$$A := \begin{bmatrix} 23 & 76 & 23 & -92 & 38 & -3 \\ -8 & -32 & -10 & 40 & -17 & 1 \\ -34 & -124 & -36 & 152 & -64 & 6 \\ -1 & -7 & -2 & 10 & -4 & 0 \\ 23 & 86 & 26 & -104 & 45 & -4 \\ 3 & 14 & 4 & -16 & 7 & 2 \end{bmatrix}$$

```
> jordan(A);
```

$$\begin{bmatrix} 2 & 1 & 0 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$

```
> p:=charpoly(A,lambda);
```

$$p := \lambda^6 - 12\lambda^5 + 60\lambda^4 - 160\lambda^3 + 240\lambda^2 - 192\lambda + 64$$

```
> factor(p);
```

$$(\lambda - 2)^6$$

```
> eigenvals(A);
```

$$2, 2, 2, 2, 2, 2$$

```
> eigenvects(A);
```

$$[2, 6, \{[0, 0, 4, 1, 0, 0], [-1, -1, 6, 0, -1, 1]\}]$$

```

> E6:=diag(1,1,1,1,1,1);

```

$$E6 := \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

```

> B:=evalm( A-2 * E6 );

```

$$B := \begin{bmatrix} 21 & 76 & 23 & -92 & 38 & -3 \\ -8 & -34 & -10 & 40 & -17 & 1 \\ -34 & -124 & -38 & 152 & -64 & 6 \\ -1 & -7 & -2 & 8 & -4 & 0 \\ 23 & 86 & 26 & -104 & 43 & -4 \\ 3 & 14 & 4 & -16 & 7 & 0 \end{bmatrix}$$

```

> B2:=evalm(B^2);

```

$$B2 := \begin{bmatrix} 8 & 30 & 9 & -36 & 15 & -1 \\ 16 & 60 & 18 & -72 & 30 & -2 \\ -36 & -140 & -42 & 168 & -70 & 6 \\ 3 & 10 & 3 & -12 & 5 & 0 \\ -8 & -30 & -9 & 36 & -15 & 1 \\ -8 & -30 & -9 & 36 & -15 & 1 \end{bmatrix}$$

```

> B3:=evalm(B^3);

```

$$B3 := \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 32 & 120 & 36 & -144 & 60 & -4 \\ 8 & 30 & 9 & -36 & 15 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

```

> B4:=evalm(B^4);

```

$$B4 := \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

```

> eigenvects(B);

```

[0, 6, {[0, 0, 4, 1, 0, 0], [-1, -1, 6, 0, -1, 1]}]

```

> eigenvects(B2);

```

[0, 6, {[0, 1, $\frac{-10}{3}$, 0, 0, 0], [0, 0, 4, 1, 0, 0], [0, 0, $\frac{-5}{3}$, 0, 1, 0], [-1, 0, 1, 0, 0, 1]}]

```

> eigenvects(B3);

```

```
[0, 6, {[0, 0, 0, 1, 0, -36], [0, 0, 1, 0, 0, 9], [0, 1, 0, 0, 0, 30], [1, 0, 0, 0, 0, 8],
[0, 0, 0, 0, 1, 15]}]
```

```
> eigenvects(B4);
```

```
[0, 6, {[1, 0, 0, 0, 0, 0], [0, 0, 0, 1, 0, 0], [0, 0, 0, 0, 1, 0], [0, 0, 0, 0, 0, 1], [0, 1, 0, 0, 0, 0],
[0, 0, 1, 0, 0, 0]}]
```

```
> X:=transpose(matrix(11,6,[0, 0, 0, 1, 0, -36,0, 0, 1, 0, 0, 9,0,
1,
0, 0, 0, 30,1, 0, 0, 0, 0, 8,0, 0, 0, 0, 1,
15,1,0,0,0,0,0,0,1,0,0,0,0,0,0,1,0,0,0,0,0,0,1,0,0,0,0,0,0,1,0,0,0,0,0,
0,0,1]));
```

$$X := \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ -36 & 9 & 30 & 8 & 15 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

```
> Y:=gaussjrd(X);
```

$$Y := \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & \frac{-15}{4} & \frac{-9}{8} & \frac{9}{2} & \frac{-15}{8} & \frac{1}{8} & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & \frac{15}{4} & \frac{9}{8} & \frac{-9}{2} & \frac{15}{8} & \frac{-1}{8} & 0 \end{bmatrix}$$

```
> v:=matrix(6,1,[1,0,0,0,0,0]);
```

$$v := \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

```
> Bv:=evalm( B &* v );
```

$$Bv := \begin{bmatrix} 21 \\ -8 \\ -34 \\ -1 \\ 23 \\ 3 \end{bmatrix}$$

```
> B2v:=evalm( B^2 &* v );
```

$$B^2v := \begin{bmatrix} 8 \\ 16 \\ -36 \\ 3 \\ -8 \\ -8 \end{bmatrix}$$

```
> XX:=transpose(matrix(7,6,[0, 0, 4, 1, 0, 0,-1, -1, 6, 0, -1,
> 1,8,16,-36,3,-8,-8,0, 1, (-10)/3, 0, 0, 0,0, 0, 4, 1, 0, 0,0,
0,
> (-5)/3, 0, 1, 0,-1, 0, 1, 0, 0, 1]));
```

$$XX := \begin{bmatrix} 0 & -1 & 8 & 0 & 0 & 0 & -1 \\ 0 & -1 & 16 & 1 & 0 & 0 & 0 \\ 4 & 6 & -36 & \frac{-10}{3} & 4 & \frac{-5}{3} & 1 \\ 1 & 0 & 3 & 0 & 1 & 0 & 0 \\ 0 & -1 & -8 & 0 & 0 & 1 & 0 \\ 0 & 1 & -8 & 0 & 0 & 0 & 1 \end{bmatrix}$$

```
> YY:=gaussjord(XX);
```

$$YY := \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & \frac{3}{16} & \frac{3}{16} \\ 0 & 1 & 0 & 0 & 0 & \frac{-1}{2} & \frac{1}{2} \\ 0 & 0 & 1 & 0 & 0 & \frac{-1}{16} & \frac{-1}{16} \\ 0 & 0 & 0 & 1 & 0 & \frac{1}{2} & \frac{3}{2} \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

```
> w:=matrix(6,1,[0,3,-10,0,0,0]);
```

$$w := \begin{bmatrix} 0 \\ 3 \\ -10 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

```
> Bw:=evalm( B &* w );
```

$$Bw := \begin{bmatrix} -2 \\ -2 \\ 8 \\ -1 \\ -2 \\ 2 \end{bmatrix}$$

```
> B3v:=evalm( B^3 &* v );
```

$$B3v := \begin{bmatrix} 0 \\ 0 \\ 32 \\ 8 \\ 0 \\ 0 \end{bmatrix}$$

> P:=Matrix([v,Bv,B2v,B3v,w,Bw]);

$$P := \begin{bmatrix} 1 & 21 & 8 & 0 & 0 & -2 \\ 0 & -8 & 16 & 0 & 3 & -2 \\ 0 & -34 & -36 & 32 & -10 & 8 \\ 0 & -1 & 3 & 8 & 0 & -1 \\ 0 & 23 & -8 & 0 & 0 & -2 \\ 0 & 3 & -8 & 0 & 0 & 2 \end{bmatrix}$$

> J:=evalm(inverse(P) &* A &* P);

$$J := \begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{bmatrix}$$